Computations with Ore Polynomial Matrices

Howard Cheng

Department of Mathematics and Computer Science University of Lethbridge, Canada

Joint work with Bernhard Beckermann, Patrick Davies, George Labahn.

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Ore Polynomials

- The ring of Ore polynomials $\mathbb{Q}_{\mathbb{D}}[X; \sigma, \delta]$
 - σ: automorphism over Q_D
 - δ : additive homomorphism on $\mathbb{Q}_{\mathbb{D}}$
 - Polynomial multiplication: $Xa = \sigma(a)X + \delta(a)$

	$\sigma(a(t))$	$\delta(a(t))$
Polynomials	a(t)	0
Differential operator	a(t)	<i>a</i> '(<i>t</i>)
Difference operator	a(t+1)	0

- $\delta = 0 \Rightarrow$ shift polynomials
- Matrices of Ore polynomials represent systems of linear differential equations, difference equations, etc.

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Problems

Given an $m \times n$ Ore polynomial matrix $\mathbf{F}(X)$ of degree N, we wish to compute:

• a basis for the left nullspace of F(X);

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• leading row coefficient of nonzero rows have full row rank and associated unimodular transformation matrix U(X);

- the Popov form of $\mathbf{F}(X)$
 - leading row coefficient is triangular (weak Popov form)
 - leading entry is monic and has highest degree in its column

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• determine the rank of a matrix of Ore polynomials;

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- compute greatest common right divisors (GCRD) and least common left multiples (LCLM) i.e. intersection and union of systems;
- reduce order of systems of equations;
- isolate highest powers.

e.g. convert DAE systems to first order.

interchange two rows

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We also wish to compute the transformation matrix in many cases.

Issues

- Straightforward elimination may introduce coefficient growth:
 - from Gaussian elimination;
 - from multiplication by X.

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 - from Gaussian elimination;
 - from multiplication by X.
- Algorithms for polynomial matrices may not work on Ore polynomial matrices.
- Proofs of correct algorithms for polynomial matrices may rely on commutativity or fractions of matrix elements.



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GCRD and LCLM of Ore polynomials (Li, Li and Nemes): normal forms of 2 × 1 Ore polynomial matrix;

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- EG elimination and improvements (Abramov, Abramov and Bronstein);

- normal forms of 2 × 1 Ore polynomial matrix;
- subresultant (fraction-free) and modular algorithms;
- EG elimination and improvements (Abramov, Abramov and Bronstein);
- many works on polynomial matrices.

Order basis

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- Order basis
- Striped Krylov matrix

- Order basis
- Striped Krylov matrix
- Equivalence of Gaussian elimination and polynomial operations

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We want the module of solutions $\mathbf{P}(X) = [P_1(X) \cdots P_m(X)]$ of order $\vec{\omega}$ such that

$$P_1(X) \cdot \mathbf{F}_{1,\cdot}(X) + \cdots P_m(X) \cdot \mathbf{F}_{m,\cdot}(X) = \mathbf{R}(X) \cdot X^{\vec{\omega}}$$

where $\mathbf{F}_{i,\cdot}(X)$ is the *i*-th row of $\mathbf{F}(Z)$, and $\mathbf{R}(X)$ is a residual.

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- A basis of the module: order basis of order $\vec{\omega}$
- An order basis represents row operations on F(X) to eliminate low-order terms.
- An order basis of a particular order and row degree is unique up to a constant.

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- It is a generalization of the Sylvester matrix.
- The entries in the matrix are commutative—traditional linear algebra applies.
- In general, we do not know the degree bound a priori.

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Fraction-free Order Basis Algorithm (FFreduce)

- Compute a sequence of order bases of increasing order and degrees:
 - order \Rightarrow column degree \Rightarrow
- ⇒ number of columns eliminated
 ⇒ number of times a row has been used as pivot

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- The elimination is done via a fraction-free recurrence.

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Let $\mathbf{M}(X)$ be an order basis of order $\vec{\omega}$ and column degree $\vec{\mu}$. Let r_j be the term of residual to be eliminated.

Let π (the pivot) be the smallest index with $r_{\pi} \neq 0$ and $\vec{\mu}_{\pi} = \min_{j} {\{\vec{\mu}_{j} : r_{j} \neq 0\}}.$

$$\widetilde{\mathsf{M}}(X)^{\ell,\cdot} = \left(r_{\pi} \cdot \mathsf{M}(X)^{\ell,\cdot} - r_{\ell} \cdot \mathsf{M}(X)^{\pi,\cdot} \right) / p_{\pi} \quad \text{for } l \neq \pi,$$

$$\widetilde{\mathsf{M}}(X)^{\pi,\cdot} = \left((r_{\pi} \cdot X - \delta(r_{\pi})) \cdot \mathsf{M}(X)^{\pi,\cdot} - \sum_{\ell \neq \pi} \sigma(p_{\ell}) \cdot \widetilde{\mathsf{M}}(X)^{\ell,\cdot} \right) / \sigma(p_{\pi}),$$

where $p_j = coefficient(\mathbf{M}(X)^{\pi,j}, X^{\vec{\mu}_j + \delta_{\pi,j}-1}).$

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- Order basis and residual of order $(mN + 1)n \cdot (1, ..., 1)$ gives:
 - rank $\mathbf{F}(X)$
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- Order basis and residual of order $(mN + 1)n \cdot (1, ..., 1)$ gives:
 - rank $\mathbf{F}(X)$
 - basis of left nullspace of **F**(Z)
- For shift polynomials:
 - reverse the coefficients
 - eliminate until the trailing coefficient *R*₀ has full rank (row-reduced form) or is triangular (weak Popov form).

Modular Algorithm

• Design a modular version to improve performance.

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- Modular reductions:

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- Three traditional issues:
 - definition and detection of unlucky homomorphisms
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- We wish to have an output-sensitive algorithm:
 - number of homomorphisms depends on the size of results
 - no need to verify the results by trial division/multiplication

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• These issues have been resolved for polynomial matrices (Cheng and Labahn).

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- The same approach does not work for $\mathbb{Z}_{p}[t][X; \sigma, \delta] \rightarrow \mathbb{Z}_{p}[X; \sigma, \delta]$:

• evaluation map $t \leftarrow \alpha$ is not an Ore ring homomorphism.

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• Compute order basis and residual in $\mathbb{Z}_p[t][X; \sigma, \delta]$.

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- Compute order basis and residual in $\mathbb{Z}_p[t][X; \sigma, \delta]$.
- Normalization: compute the image of the same order basis and residual as FFreduce.
- Chinese remaindering used to reconstruct the result.

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- i.e. lucky homomorphism ⇔ same endpoint as FFreduce.
- Homomorphisms with different endpoints: the one that is further away from a "normal path" is unlucky.

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For the remainder of this talk, we assume that:

$$\mathsf{deg}_t\left(\boldsymbol{c}_k\left(\boldsymbol{X}^\ell\cdot\mathbf{F}(\boldsymbol{X})_{i,j}\right)\right) \leq T$$
$$\left\|\boldsymbol{c}_k\left(\boldsymbol{X}^\ell\cdot\mathbf{F}(\boldsymbol{X})_{i,j}\right)\right\|_{\infty} \leq \kappa$$

for $1 \le i \le m$, $1 \le j \le n$, $0 \le k < mN + 1$, and $0 \le \ell \le mN + 1$ where $N = \deg \mathbf{F}(X)$.

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- Suppose $p_1 < p_2 < \cdots$, and τ is such that

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- Reconstructed results have not changed for *τ* additional primes ⇒ reconstructed results are correct
- τ is small in many cases (e.g. 1).

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- Evaluation homomorphisms t ← α are not an Ore ring homomorphism in general.
- We cannot simply apply the reductions and reconstruct the results as before.

 Modular algorithms to compute GCRDs of Ore polynomials (Li and Nemes):

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- Modular algorithms to compute GCRDs of Ore polynomials (Li and Nemes):
 - Gaussian elimination on Sylvester matrix
 - use modular algorithm on Sylvester matrix
- This is not straightforward for matrices of Ore polynomials:
 - the computation path (degree bound) is not known a priori
 - it is not known a priori which striped Krylov matrix is needed
We interleave the construction of the striped Krylov matrix with elimination steps:

- when an elimination step is performed, a new row is added (after evaluation homomorphism is applied)
- the added row is reduced with respect to all previous pivot rows

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- Normalization: same as the case Z_p[t][X; σ, δ]
- Lucky homomorphisms: similar as Z_p[t][X; σ, δ]
- Termination:

results unchanged for T additional homomorphisms \Rightarrow reconstructed results are correct

Example

$$\mathcal{K}(\vec{\mu},\vec{\omega}) = \begin{bmatrix} 6t^2 & 2 & 3t & -1 & 2 & 1 \\ 12t & 0 & 6t^2 + 3 & 2 & 3t & -1 \\ 12 & 0 & 24t & 0 & 6t^2 + 6 & 2 \\ \hline 3t^3 & t & t - 1 & 3t & 0 & 0 \\ 9t^2 & 1 & 3t^3 + 1 & t + 3 & t - 1 & 3t \\ 18t & 0 & 18t^2 & 2 & 3t^3 + 2 & t + 6 \end{bmatrix}$$

 The substitution t ← 0 gives a completely different pivot choice (third row).

In general, pivot rows and columns correct at the end \Rightarrow the evaluation is lucky

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- Order basis computation eliminates low-order terms.
- For shift polynomials, leading term can be eliminated by reversing coefficients.
- In general, this is not possible.
- Popov form cannot be computed directly with order basis even for shift polynomials.

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$$\begin{bmatrix} \mathbf{F}(X) \cdot X^b \\ -I \end{bmatrix}$$

Howard Cheng Computations with Ore Polynomial Matrices

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• The left nullspace can be partitioned as:

$$\mathbf{M}(X) = \begin{bmatrix} \mathbf{U}(X) & \mathbf{T}(X) \cdot X^b \end{bmatrix}$$

so

$$\mathbf{U}(X) \cdot \mathbf{F}(X) \cdot Z^b = \mathbf{T}(X) \cdot X^b$$

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 If b > deg U(X), then the leading row coefficient of M(X) is the leading row coefficient of T(X).

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- If b > deg U(X), then the leading row coefficient of M(X) is the leading row coefficient of T(X).
- $\mathbf{M}(Z)$ in Popov form $\Leftrightarrow \mathbf{T}(Z)$ in Popov form.
- Old idea, but proofs do not work when matrix entries are not commutative.

Let $\vec{\mu} = \text{rdeg } \mathbf{F}(X)$ and $b > |\vec{\mu}| - \min_j \{\mu_j\}$.

Suppose that $[\mathbf{U}(X) \ \mathbf{R}(X)]$ is a minimal polynomial basis in Popov form of the left nullspace of $\begin{bmatrix} \mathbf{F}(X) \cdot X^b \\ -\mathbf{I} \end{bmatrix}$.

Let
$$\mathbf{T}(X) = \mathbf{R}(X) \cdot X^{-b}$$
.

- **U**(X) is unimodular;
- **2** $\mathbf{T}(X) = \mathbf{U}(X) \cdot \mathbf{F}(X)$ is an Ore polynomial matrix in Popov form.

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- Elimination is formulated as linear systems of equations on the coefficients.
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- Polynomial arithmetic is used to take advantange of the matrix structure.

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Howard Cheng Computations with Ore Polynomial Matrices



Example

Let
$$\vec{\mu} = (2,2), \ \vec{\omega} = (3,3), \text{ and}$$

$$\mathbf{F}(X) = \begin{bmatrix} 2X^2 + 3tX + 6t^2 & X^2 - X + 2\\ (t-1)X + 3t^3 & 3tX + t \end{bmatrix} \in \mathbb{Z}[t][X; \sigma, \delta]^{2 \times 2},$$
with $\sigma(\mathbf{a}(t)) = \mathbf{a}(t)$ and $\delta(\mathbf{a}(t)) = \mathbf{a}'(t).$

$$\frac{X^0 \qquad X^1 \qquad X^2}{12t \ 0 \ 6t^2 + 3 \ 2 \ 3t \ -1} \qquad \frac{2}{12t \ 0 \ 6t^2 + 3 \ 2 \ 3t \ -1} \qquad \frac{2}{3t^3 \ t \ t-1 \ 3t \ 0 \ 0} \qquad 0}{9t^2 \ 1 \ 3t^3 + 1 \ t+3 \ 1t-1 \ 3t} \qquad 0 \ 0}.$$



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